# Augment and Reduce: Stochastic Inference for Large Categorical Distributions

Francisco J. R. Ruiz

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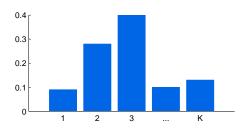




## Joint Work With



## Categorical Distributions



- ▶ A probability distribution on a set of *K* outcomes
- ▶ Normalized,  $\sum_k p_k = 1$
- ▶ Ubiquitous in machine learning and many other disciplines

#### Our Contribution

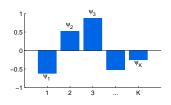
- lacktriangle Goal: Speed up training for models with large categoricals  $(K\gg 1)$
- ▶ Contribution: A fast algorithm with controlled complexity
- ▶ Key ideas: Variable augmentation, stochastic variational inference

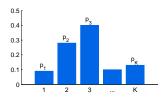
#### Softmax

▶ One widely applied parameterization of a categorical,

$$p(y=k \mid \psi) = \frac{e^{\psi_k}}{\sum_{k'} e^{\psi_{k'}}}$$

▶ Transforms reals into probabilities





- ▶ Observations are features and labels,  $\{x_n, y_n\}_{n=1}^N$
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- ▶ Each label  $y_n \in \{1, ..., K\}$
- ▶ Each observation *n* is assigned a real value,

$$\psi_k^{(n)} = \mathbf{w}_k^{\top} \mathbf{x}_n$$

▶ Goal: Find the weights  $w = (w_1, ..., w_K)$ 

▶ Maximize the likelihood of the data w.r.t. the weights,

find 
$$w$$
 to maximize  $\mathcal{L}_{\text{log-lik}} = \sum_{n} \log p(y_n \mid x_n, w)$ 

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Assuming the softmax transformation,

$$\log p(y_n \mid x_n, w) = \log \left( \frac{e^{w_{y_n}^\top x_n}}{\sum_{k'} e^{w_{k'}^\top x_n}} \right)$$

- ▶ Optimization w.r.t. w
- Gradient ascent

$$\begin{array}{c} w^{(0)} \\ \times \\ w^{(1)} \\ \times \\ \times \end{array} \times \begin{array}{c} w^{(2)} \\ \times \\ \end{array} \times \begin{array}{c} w^{(3)} \\ \end{array}$$

► The gradient is

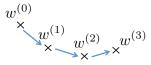
$$\nabla_{w} \mathcal{L}_{\text{log-lik}} = \sum_{n} \nabla_{w} \log p(y_{n} | x_{n}, w)$$

$$\nabla_w \log p(y_n \mid x_n, w) = \nabla_w \log \left( \frac{e^{w_{y_n}^\top x_n}}{\sum_{k'} e^{w_{k'}^\top x_n}} \right)$$

**Problem:** Evaluating the gradient is  $\mathcal{O}(K)$ 

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For large values of K, this is prohibitive

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- ▶ The  $\mathcal{O}(K)$  cost is not unique to the softmax
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- ▶ When K is large, this is not OK
- ► Examples: language models, recommendation systems, discrete choice models, reinforcement learning

#### Our Contribution

- $\blacktriangleright$  An algorithm with reduced complexity,  $\mathcal{O}(|\mathcal{S}|)$  instead of  $\mathcal{O}(K)$
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- lacktriangleright Complexity controlled by parameter  $|\mathcal{S}|$
- ► Two steps
  - 1. Augment the model with an auxiliary variable
  - 2. Reduce complexity via subsampling (stochastic optimization)

## Let's Take A Step Back...

▶ Where does the softmax come from?

$$p(y=k \mid \psi) = \frac{e^{\psi_k}}{\sum_{k'} e^{\psi_{k'}}}$$

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▶ Integrate out the error terms  $(\varepsilon_k$ 's) to find the marginal  $p(y \mid \psi)$ 

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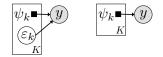
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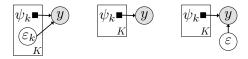
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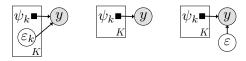
 Other models: multinomial probit (Gaussian prior), multinomial logistic (logistic prior)







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- Work with the joint  $p(y, \varepsilon | \psi)$
- ▶ Nice property: Amenable to stochastic optimization

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► This is an integral,

$$p(y = k | \psi) = \int_{-\infty}^{+\infty} \phi(\varepsilon_k) \left( \prod_{k' \neq k} \int_{-\infty}^{\varepsilon_k + \psi_k - \psi_{k'}} \phi(\varepsilon_{k'}) d\varepsilon_{k'} \right) d\varepsilon_k$$

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Augment the model,

$$p(y = k, \varepsilon | \psi) = \phi(\varepsilon) \prod_{k' \neq k} \Phi(\varepsilon + \psi_k - \psi_{k'})$$

## The Augmented Model

▶ We now have the augmented model,

$$p(y = k, \varepsilon | \psi) = \phi(\varepsilon) \prod_{k' \neq k} \Phi(\varepsilon + \psi_k - \psi_{k'})$$



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- This enables fast unbiased estimates,
  - 1. Sample a subset of outcomes  $S \subseteq \{1, ..., K\} \setminus \{k\}$  of fixed size |S|
  - 2. Compute an estimate of the log-joint in  $\mathcal{O}(|\mathcal{S}|)$  complexity

$$\log \phi(\varepsilon) + \frac{K-1}{|\mathcal{S}|} \sum_{k' \in \mathcal{S}} \log \Phi(\varepsilon + \psi_k - \psi_{k'})$$

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- ▶ Maximize the bound using variational EM
  - 1. E step: Optimize w.r.t. the distribution  $q(\varepsilon)$
  - 2. M step: Take a gradient step w.r.t.  $\psi$  (or its parameters w)

Recall the classification objective,

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Replace each term with its variational bound,

$$\mathcal{L}_{\text{bound}} = \sum_{n} \mathbb{E}_{q(\varepsilon^{(n)})} \left[ \log p(y_n, \varepsilon^{(n)} | x_n, w) - \log q(\varepsilon^{(n)}) \right]$$

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- Algorithm
  - 1. Subsample datapoints  $\mathcal{B} \subseteq \{1, \dots, N\}$
  - 2. For each  $n \in \mathcal{B}$ , subsample classes  $\mathcal{S} \subseteq \{1, \dots, K\} \setminus \{y_n\}$
  - 3. (E step) For each  $n \in \mathcal{B}$ , update its  $q(\varepsilon^{(n)})$   $\mathcal{O}(|\mathcal{S}|)$
  - 4. (M step) For each  $n \in \mathcal{B}$ , compute gradient w.r.t. w  $\mathcal{O}(|\mathcal{S}|)$
  - 5. (M step) Take gradient step for w
  - 6. Repeat

▶ Recall the log-joint in the augmented model,

$$\log p(y = k, \varepsilon \mid \psi) = \log \phi(\varepsilon) + \sum_{k' \neq k} \log \Phi(\varepsilon + \psi_k - \psi_{k'})$$



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► Consider the gradient of the bound in the M step,

$$\nabla_{w} \mathcal{L}_{\text{bound}} = \nabla_{w} \sum_{n} \mathbb{E}_{q(\varepsilon^{(n)})} \left[ \log p(y_{n}, \varepsilon^{(n)} \mid x_{n}, w) - \log q(\varepsilon^{(n)}) \right]$$

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$$q^{\star}(\varepsilon) = \operatorname{Gumbel}(\log \eta, 1)$$

Estimate the optimal natural parameter,

$$\widetilde{\eta} = 1 + \frac{K - 1}{|S|} \sum_{k' \in S} e^{\psi_{k'} - \psi_k}$$

(to update  $\eta$ , take a step in the direction of the natural gradient)

## Augment & Reduce For Other Models

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- ▶ For other models, the expectations are intractable
- ► We form Monte Carlo gradient estimators using the reparameterization trick
- Useful for both E and M steps

- ► Experiments: Linear classification
- ▶ Maximum likelihood estimation
- ▶ 5 datasets

$N_{\mathrm{train}}$	$N_{ m test}$	covariates	classes	minibatch (obs.)	minibatch (classes)	iterations
60,000	10,000	784	10	500	1	35,000
4,880	2,413	1,836	148	488	20	5,000
25,968	6,492	784	1,623	541	50	45,000
15,539	3,809	5,000	896	279	50	100,000
1,186,239	306,782	203,882	2,919	1,987	60	5,970
	60,000 4,880 25,968 15,539	60,000 10,000 4,880 2,413 25,968 6,492 15,539 3,809	60,000 10,000 784 4,880 2,413 1,836 25,968 6,492 784 15,539 3,809 5,000	60,000 10,000 784 10 4,880 2,413 1,836 148 25,968 6,492 784 1,623 15,539 3,809 5,000 896	60,000         10,000         784         10         500           4,880         2,413         1,836         148         488           25,968         6,492         784         1,623         541           15,539         3,809         5,000         896         279	

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  - One-vs-each (OVE) bound,

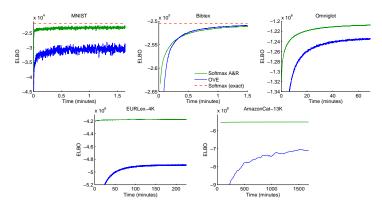
$$\mathcal{L}_{ ext{OVE}} = \sum_{k' 
eq k} \log \sigma (\psi_k - \psi_{k'})$$

(it is a bound on the softmax)

#### ► Time complexity

dataset	OVE (Titsias, 2016)	softmax	A&R [this paper] multi. probit multi. logistic			
MNIST	0.336 s	0.337 s	0.431 s	0.511 s		
Bibtex	0.181 s	0.188 s	0.244 s	0.246 s		
Omniglot	4.47 s	4.65  s	5.63 s	5.57 s		
EURLex-4K	5.54  s	5.65  s	6.46 s	6.23 s		
AmazonCat-13K	2.80 h	2.80 h	2.82 h	2.91 h		

#### ▶ Quality of the bound



#### ightharpoonup Quality of the classification weights $w_k$ (predictive performance)

dataset	exa log lik	ct acc	softma OVE (Tits log lik	x model ias, 2016) acc	A&R [this paper] log lik acc		multi. probit A&R [this paper] log lik acc		multi. logistic A&R [this paper] log lik acc	
MNIST Bibtex Omniglot EURLex-4K AmazonCat-13K	-0.261 -3.188 - -	0.927 0.361 - -	-0.276 -3.300 -5.667 - <b>4.241</b> -3.880	0.919 0.352 0.179 <b>0.247</b> 0.388	-0.271 -3.036 -5.171 -4.593 -3.795	0.924 0.361 0.201 0.207 0.420	-0.302 -4.184 -7.350 -4.193 -3.593	0.918 0.346 0.178 0.263 0.411	-0.287 -3.151 -5.395 -4.299 -4.081	0.917 0.353 0.184 0.226 0.350

#### Conclusion

- A method to scale up training for models involving large categorical distributions
- Stochastic variational EM
- ▶ Controlled complexity (|S| is a parameter)
- Can be embedded in many different models
- ▶ Not limited to maximum likelihood estimation

# Thank you for your attention!

